

# Imputation under Missing at Random

How to Impute and How to Evaluate Imputations

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The logo for Inria, featuring the word "Inria" in a red, cursive script font.

## Adding Parameters

- Assume  $p^*$  is parametrized by a vector  $\theta$  and  $\mathbb{P}(M = m | x)$  is parametrized by a vector  $\phi$ .
- Rewrite the MAR definition slightly:

$$\mathbb{P}_\phi(M = m|x) = \mathbb{P}_\phi(M = m|o(x, m)) \text{ for all } m \in \mathcal{M} \text{ and } x. \quad (1)$$

(just added  $\phi$ )

- $\theta$  is the vector of interest,  $\phi$  is a nuisance parameter

# 1. Ignorability and Maximum Likelihood

2. Uncertainty Adjustment

3. Conclusion

## Rubin's Original Result

- Assume MAR holds + that “ $\theta$  and  $\phi$  are distinct”
- Should just mean that  $\mathbb{P}_\phi(M = m|x)$  does not depend on  $\theta$ . For every fixed  $\phi$  we can choose  $\theta$  freely and the other way around
- Now assume we want to find  $\theta$  with Maximum Likelihood Estimation (MLE).
- Without missing values:

$$\hat{\theta} = \arg \max_{\theta} p_{\theta}^*(x).$$

## Rubin's Original Result

- Consider the likelihood for a pattern  $m \in \mathcal{M}$ ,

$$\begin{aligned}\mathcal{L}(\theta; o(x, m)) &= \int p_{\theta, \phi}^*(x, M = m) d\mathcal{O}^c(x, m) \\ &= \int \mathbb{P}_{\phi}(M = m | x) p_{\theta}^*(x) d\mathcal{O}^c(x, m) \\ &= \mathbb{P}_{\phi}(M = m | o(x, m)) p_{\theta}^*(o(x, m)) \\ &= c(o(x, m)) p_{\theta}^*(o(x, m)).\end{aligned}$$

$c(o(x, m))$  does not depend on  $\theta$ . So for all  $m \in \mathcal{M}$ :

$$\hat{\theta} = \arg \max_{\theta} \mathcal{L}(\theta; o(x, m)) = \arg \max_{\theta} p_{\theta}^*(o(x, m)) \quad (2)$$

## Rubin's Original Result

- This in particular means that for an i.i.d. sample:

$$\begin{aligned}\hat{\theta} &= \arg \max_{\theta} \prod_{i=1}^n \mathcal{L}(\theta; o(X_i, M_i)) \\ &= \arg \max_{\theta} \prod_{i=1}^n p_{\theta}^*(o(X_i, M_i))\end{aligned}$$

$\Rightarrow$  The whole story with different patterns and different distribution from the first part doesn't really matter here(!)

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This is nice, but the optimization often gets quite complicated, and **EM algorithms** have to be employed.

1. Ignorability and Maximum Likelihood

## **2. Uncertainty Adjustment**

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## Rubin's Rules

- If imputation is used, one has to be careful to not underestimate the variability of parameters
- Even if the values are now imputed, the fact that we didn't observe them introduces additional uncertainty

# Rubin's Rules

- Assume we have generated  $m$  datasets

$X_1$	$X_2$	$X_3$	Y
3	20	10	s
-6	45	6	s
0	4	30	no s
-4	32	35	s
1	63	40	s
-2	15	12	no s

$X_1$	$X_2$	$X_3$	Y
-7	20	10	s
-6	45	9	s
0	12	30	no s
13	32	35	s
1	63	40	s
-2	10	12	no s

$X_1$	$X_2$	$X_3$	Y
7	20	10	s
-6	45	12	s
0	-5	30	no s
2	32	35	s
1	63	40	s
-2	20	12	no s

- Calculate  $\hat{\theta}_j$  and  $\hat{v}ar(\hat{\theta}_j)$ , for  $j = 1, \dots, m$ .
- Combine using Rubin's Rules:

$$\hat{\theta} = \frac{1}{m} \sum_j \hat{\theta}_j$$

$$T = \underbrace{\frac{1}{m} \sum_j \hat{v}ar(\hat{\theta}_j)}_{\text{within variance}} + \underbrace{\left(1 + \frac{1}{m}\right) \frac{1}{m-1} \sum_j (\hat{\theta}_j - \hat{\theta})^2}_{\text{between variance}}$$

## Something we ignored

- Despite our careful analysis there is something we forgot
- For the above rules to be truly valid, an imputation should also include *model uncertainty*
- For instance in the Gaussian Imputation, the regression estimator  $\hat{\beta}$  has some error in finite samples that should be accounted for.
- This might be a reason to use mice-rf over mice-cart, as mice-rf attempts to account for this by using different trees
- However this is somewhat negligible for larger sample sizes.

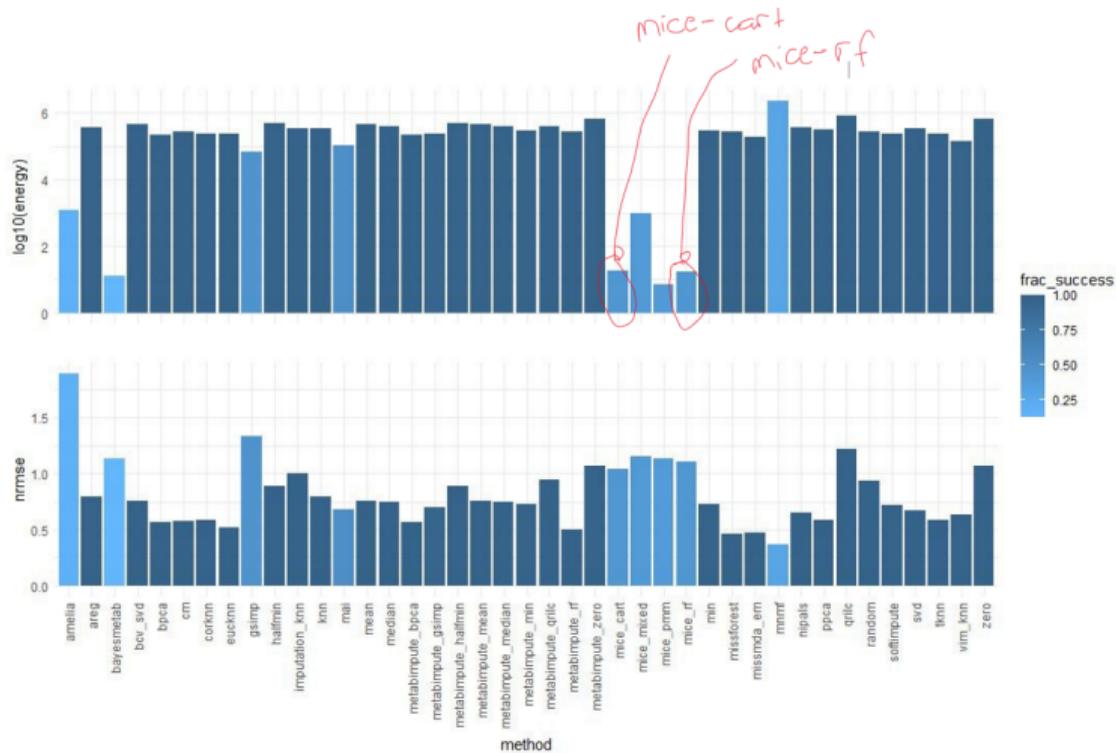
1. Ignorability and Maximum Likelihood

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## What Method to use?

- In terms of distributional distance, **mice-cart/RF/DRF** seem almost unbeatable for real data with a number of observations  $n > 200$
- For  $n \leq 200$ , “**mice-pmm**” might even work a bit better



**Figure:** Preliminary Figure, showing the performance of a range of imputation methods for metabolomics data. The datasets and missing methods are described here

## So which Imputation Method?

- In terms of distributional distance, **mice-cart/RF/DRF** seem almost unbeatable for real data with a number of observations  $n > 200$
- For  $n \leq 200$ , “**mice-pmm**” might even work a bit better
- It could however be that these observations are a result of researchers not using realistic MAR assumptions (!)
- For instance, researchers often use the `ampute` function of the `mice` package.
- This function does not appear to induce heavy distributional shifts.

## Some Helpful Links

- Rmisstastic
- Imputomics
- mice package vignette
- CRAN Task view on missing data

# Bibliography

*Inria*